

① $F = \frac{GMm}{R^2} \Rightarrow g = \frac{GM}{R^2}$ since $F = mg$

$\rho = \frac{M}{V}$ $M = \rho V \Rightarrow g = \frac{G\rho V}{R^2}$

But $V = \frac{4}{3}\pi R^3 \Rightarrow g = \frac{G\rho \frac{4}{3}\pi R^3}{R^2} = \frac{4G\rho\pi}{3} R$

$\frac{g_1}{g_2} = \frac{R_1}{R_2}$ [D]

② \vec{F} is \perp to the path $\Rightarrow \vec{F} \cdot d\vec{r} = 0 \Rightarrow W = 0$ [C]

③ $\frac{1}{2} m v_{esc}^2 = \frac{GMm}{R}$ $v_{esc}^2 = \frac{2GM}{R}$ But $g = \frac{GM}{R^2}$ from question 1

$\Rightarrow v_{esc}^2 = 2gR \Rightarrow v_{esc} = \sqrt{2gR}$

If $g \rightarrow 4g$ & $R \rightarrow 4R$ $v_{esc} \rightarrow \sqrt{2(4g)(4R)} = 4\sqrt{2gR} = \underline{\underline{4v_{esc}}}$ [B]

④ Steel has larger density than wood

$\Rightarrow I_1 > I_2$ $\tau_1 = \tau_2$ $\tau = I\alpha$

$I_1\alpha_1 = I_2\alpha_2$ $\alpha_1 = \frac{I_2}{I_1}\alpha_2$ $\Rightarrow \alpha_1 < \alpha_2$ [B]

⑤ Conservation of angular momentum -

At A and B the velocity vector is perpendicular to the radial vector

$L_A = m v_A R_A = m v_A R$

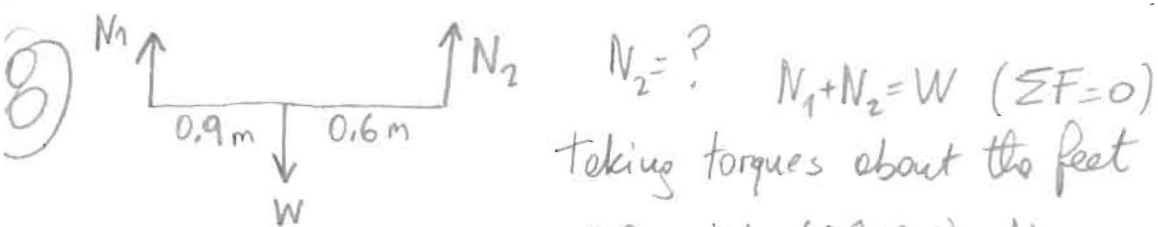
$L_B = m v_B R_B = 3m v_B R$

$L_A = L_B$ gives $m v_A R = 3m v_B R \Rightarrow v_A = 3v_B$ [B]

6) $\alpha = \frac{\Delta\omega}{\Delta t} = \frac{(300-100) \text{ rpm}}{2 \text{ min}} = 100 \frac{\text{revolutions}}{\text{min}^2}$ (2)

1 revolution = 2π rad $\alpha = \frac{200\pi \text{ rad}}{\text{min}^2}$ [D]

7) The horizontal components of T_1 and T_3 are $T_1 \cos \alpha$ [A]



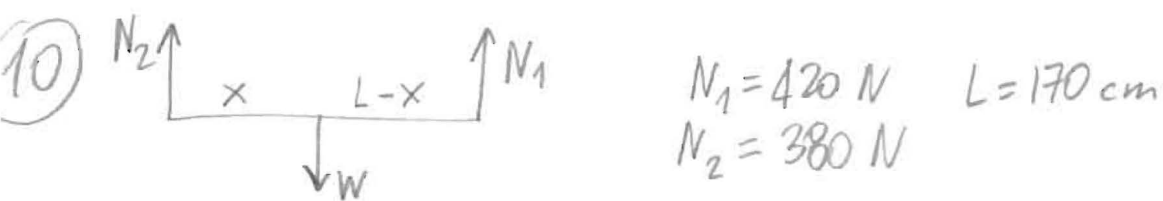
taking torques about the feet

$$0.9 \text{ m} \cdot W = (0.9 + 0.6) \text{ m} N_2$$

$$N_2 = \frac{0.9}{1.5} W = \frac{0.9}{1.5} 469.8 \text{ N} = \underline{\underline{270 \text{ N}}}$$
 [B]

9) Take torques about the hinge - $d =$ length of strut

$$100 \text{ N} \times d = T_2 \times d \times \sin 30 \quad T_2 = \frac{100 \text{ N}}{\sin 30} = \underline{\underline{200 \text{ N}}}$$
 [B]



$$\Sigma F = 0 \Rightarrow N_1 + N_2 = W \Rightarrow W = 800 \text{ N}$$

$\Sigma \tau = 0$, take torques around feet

$$Wx = N_1 L \quad x = \frac{N_1 L}{W} = \frac{420}{800} 170 \text{ cm} \quad x = \underline{\underline{89.25 \text{ cm}}}$$
 [D]

11) The speed is at maximum as we travel through the equilibrium position. At equilibrium $F = 0$ therefore $a = 0$ [D]

(3)

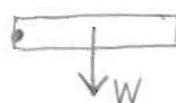
2) $\omega = \frac{2\pi}{T} \Rightarrow \omega = \pi / \text{sec}$

$x = A \cos(\omega t + \phi)$ $\begin{cases} x_0 = A \cos \phi & (1) \\ v_0 = -\omega A \sin \phi & (2) \end{cases}$ $x_0 = 20 \text{ cm}$
 $v_0 = 40 \text{ cm/sec}$

(2)/(1) gives $-\pi \tan \phi = \frac{v_0}{x_0}$ $\tan \phi = -\frac{1}{\pi} \frac{v_0}{x_0} = -\frac{1}{\pi} \frac{40}{20}$ $\phi = -32.4^\circ$
 $\phi = -0.567$

From equation (1): $A = \frac{x_0}{\cos \phi} = \frac{20 \text{ cm}}{0.84356} = \underline{\underline{23.70 \text{ cm}}}$ A

3) $F = -kx = ma \Rightarrow a = -\frac{k}{m}x$
 $a = -\frac{10}{0.5} 3 \cdot 10^{-2} \text{ m/sec}^2 = \underline{\underline{0.6 \text{ m/sec}^2}}$ A

4)  $\tau = \frac{WL}{2} = \frac{MgL}{2}$ $\tau = I\alpha = \frac{ML^2}{3}\alpha \Rightarrow \frac{MgL}{2} = \frac{ML^2}{3}\alpha$
 $\alpha = \frac{3}{2} \frac{g}{L} = \frac{3}{2} \frac{9.8}{4} \frac{\text{rad}}{\text{sec}^2} = \underline{\underline{\alpha = 3.68 \frac{\text{rad}}{\text{sec}^2}}}$ B

5) $Mgh = K_{\text{TRANSL}} + K_{\text{ROT}}$ $K_{\text{ROT}} = \frac{1}{2} I \omega^2 = \frac{1}{2} I \frac{v^2}{R^2} = \frac{1}{2} MR^2 \frac{v^2}{R^2} = \frac{1}{2} Mv^2$
 $K_{\text{TRANSL}} = \frac{1}{2} Mv^2$
 $\Rightarrow Mgh = Mv^2$
 $v = \sqrt{gh} = \sqrt{9.8 \cdot 3} \text{ m/sec} = 5.4 \text{ m/sec}$ C

6) $I_1 \rightarrow I_2$ $\omega_1 \rightarrow \omega_2$ Conservation of angular momentum $I_1 \omega_1 = I_2 \omega_2$
 $I_1 > I_2$ $\omega_2 = \frac{I_1}{I_2} \omega_1$
Initially $K_1 = \frac{1}{2} I_1 \omega_1^2$
Finally $K_2 = \frac{1}{2} I_2 \omega_2^2 = \frac{1}{2} I_2 \frac{I_1^2}{I_2^2} \omega_1^2 = \frac{1}{2} \left(\frac{I_1}{I_2}\right) I_1 \omega_1^2 = \frac{I_1}{I_2} K_1$
Since $\frac{I_1}{I_2} > 1$, $\underline{\underline{K_2 > K_1}}$ B

17) \boxed{D} $\frac{F/A}{\Delta l/l} = Y$

(4)

18) $\rightarrow F = \frac{Y}{l} A \Delta l$ $A \propto d^2 \Rightarrow F \propto d^2$ \boxed{A}

19) $E = U + K$ $E = U_{MAX} = \frac{1}{2} k A^2$
U and K will be the same when $K = U = \frac{1}{2} E = \frac{1}{4} k A^2$
 $\hookrightarrow \frac{1}{2} k x^2 = \frac{1}{4} k A^2 \Rightarrow x^2 = \frac{A^2}{2}, \boxed{x = \frac{A}{\sqrt{2}}}$
 \boxed{A}

20) $E = U(x=0) = 22 \text{ J}$

$E = U(x=2\text{m}) + K(x=2\text{m})$

$22 \text{ J} = 10 \text{ J} + \frac{1}{2} m v^2$

$12 \text{ J} = \frac{1}{2} m v^2$

$v^2 = \frac{24 \text{ J}}{2 \text{ Kg}} = 12 \frac{\text{m}^2}{\text{s}^2}$

$\boxed{v = 3.5 \text{ m/sec}}$

\boxed{C}