

VectorsTopics

- Definition
- Manners of Description
 - magnitude and direction
 - components, unit + base vectors
- "position" of a vector is elusive
 - translation usually conceptually OK
 - occasionally vector is "nailed down"
- Addition
 - geometric → "head to tail"
 - components.
- Multiplication by a scalar
 - scalar can be negative, which reverses direction of the vector
- Products of 2 Vectors
 - Dot Product or "Scalar" Product
 - * Geometric
 - * Algebraic
 - * "How much of one vector is along direction of another?"
 - Cross Product or "Vector" Product, "3-d"
 - * Geometric
 - * Algebraic
 - * "How much of one vector is \perp to direction of another?"
 - Tension Product
 - heat transfer

- Velocity + Acceleration Vectors

$\rightarrow [x(t), y(t), z(t)]$ parameterization

\rightarrow circular motion

Vector... a quantity with both magnitude and direction

"a directed line segment"

Not just a real number, because of direction

notation: books - \mathbf{A} (bold-face A)
writing - \vec{A}  arrow on top indicates

magnitude: $|\vec{A}| = \text{positive (or 0) real #}$ direction.

Vectors can live in any number of dimensions.

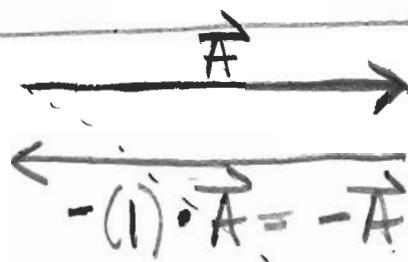
Spatial dimensions are special because we have intuitive ideas about rotations + translations.. spatial vectors transform under rotations.

One Dimension (horizontal)



$|A|$ magnitude \rightarrow direction \rightarrow left to right = adequate
magnitude is don't need to be fancy!
only one other direction. right to left.

Multiplying by -1 reverses direction of a vector



"Parallel Translation" →

(maintain direction)

+ length, but more

\vec{A} → a vector \vec{A}

$$\vec{A}$$

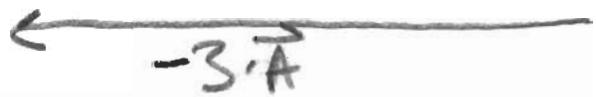
$$\vec{A}$$

Multiplying by a real number (a.k.a. a scalar) does the following:

i) changes the magnitude to $|b|\vec{A}|$

ii) if $b < 0$, reverses direction of \vec{A}

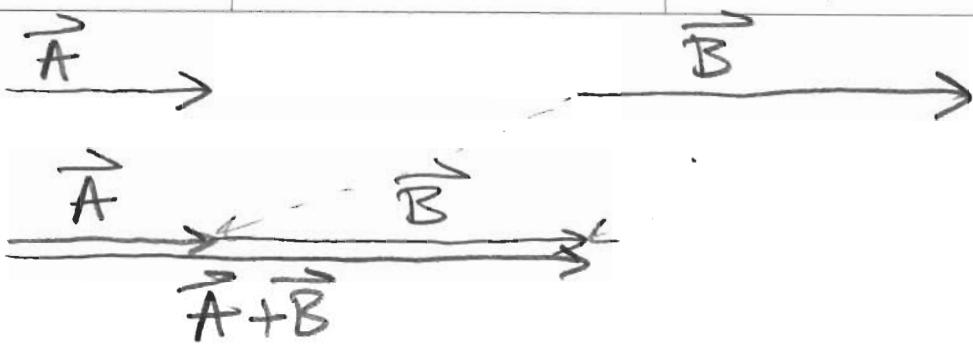
(still in one dimension!)



Adding Vectors: \vec{A} and \vec{B} , to get $\vec{A} + \vec{B}$, do parallel translation of \vec{B} so its tail is on top of \vec{A} 's tip

"Elephant Walk"





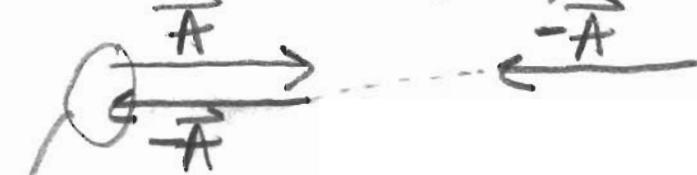
In one dimension, this is kind of trivial.

\vec{A} → like real number A

\vec{B} → like real number B

$\vec{A} + \vec{B}$ → like $A + B$

note: $\vec{A} + (-\vec{A}) =$



$\vec{A} + (-\vec{A}) = \vec{0}$ or 0 as expected.

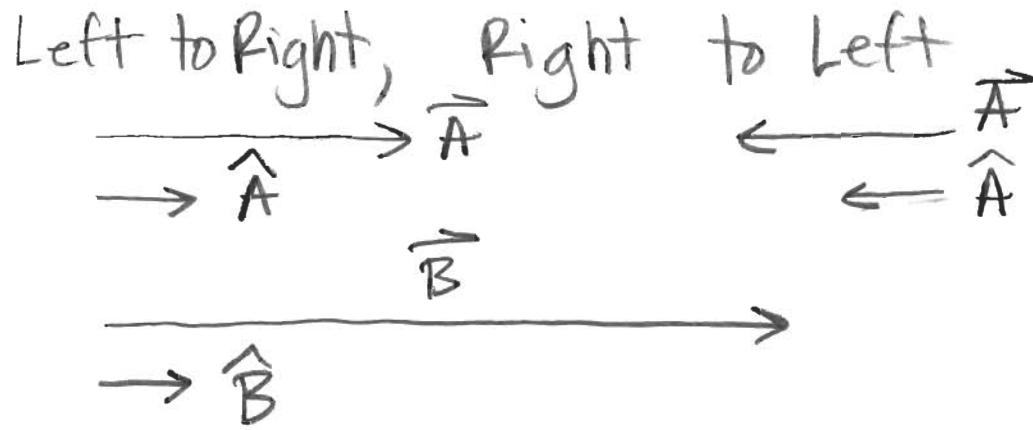
Unit vector → can be constructed from any non-zero vector

to do it: $\hat{A} = \frac{\vec{A}}{|\vec{A}|}$ = unit vector in \vec{A} direction

→ has no dimensions!

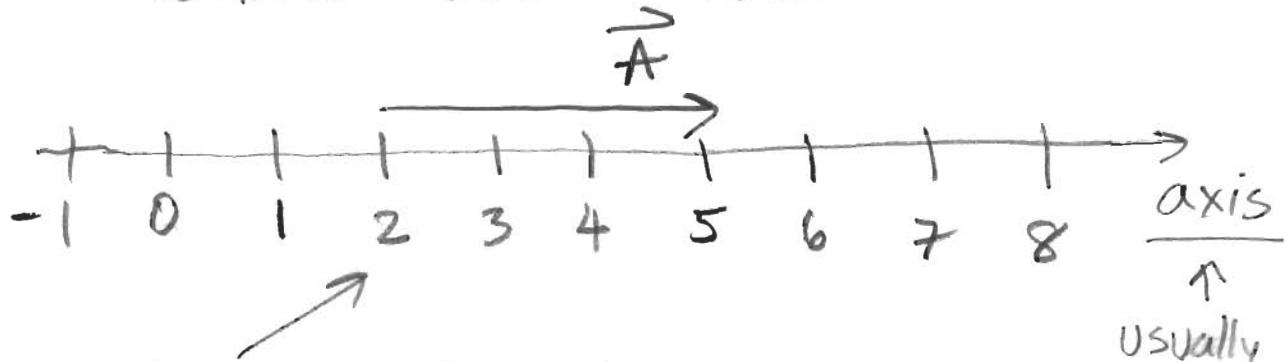
$$|\text{unit vector}| = 1 = \frac{|\vec{A}|}{|\vec{A}|} = 1$$

in one dimension, only has 2 possible directions!



Base Vectors . (1 dimension still)

→ hold up a number line to your vector... like a ruler



usually
x-axis in 1-d

- when \vec{A} is a displacement, meters etc
- " velocity, m/s etc
- " an acceleration m/s² etc

useful to define a unit vector in the direction of increasing x ... call that

\hat{i} ← when handwritten; \mathbf{i} is boldface in text.

then... $\vec{A} = A_x \hat{i}$ → defines direction.

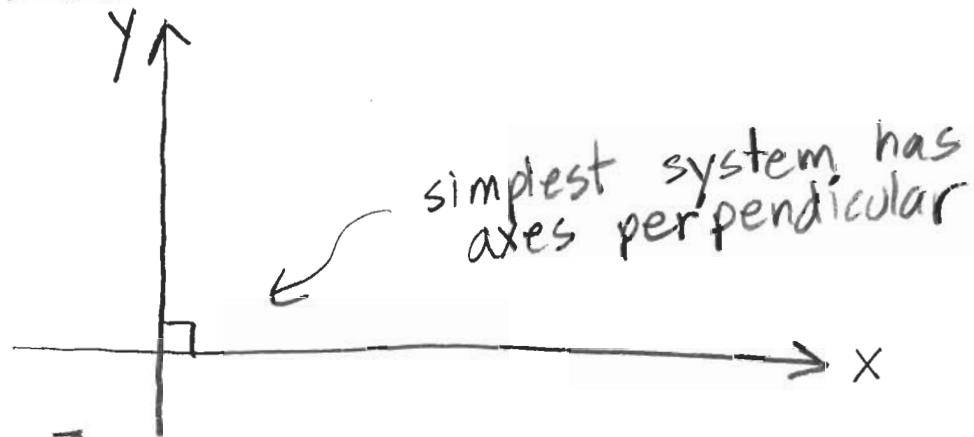
magnitude

+ or - gives direction

A_x called "x-component"

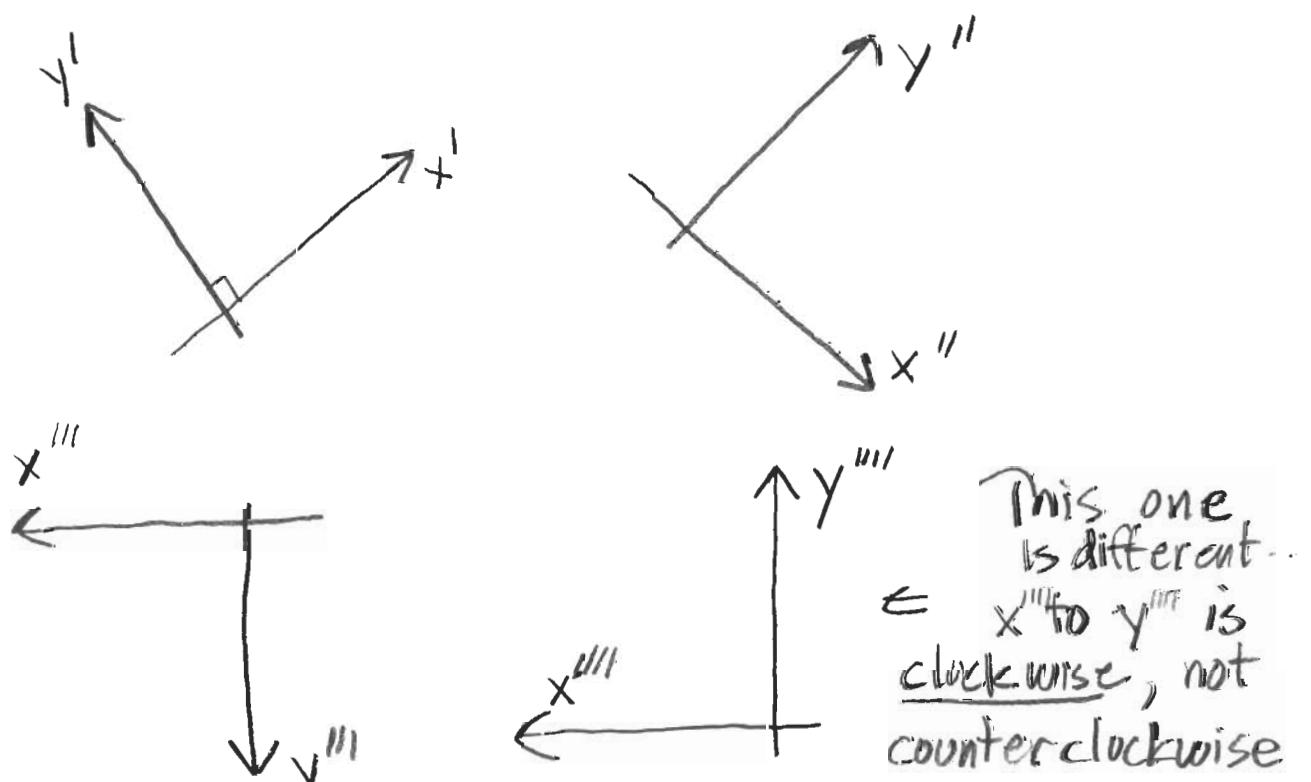
Two Dimensions

Now imagine, say, a plane. Need two axes to describe points in a plane... and 2-d vectors.



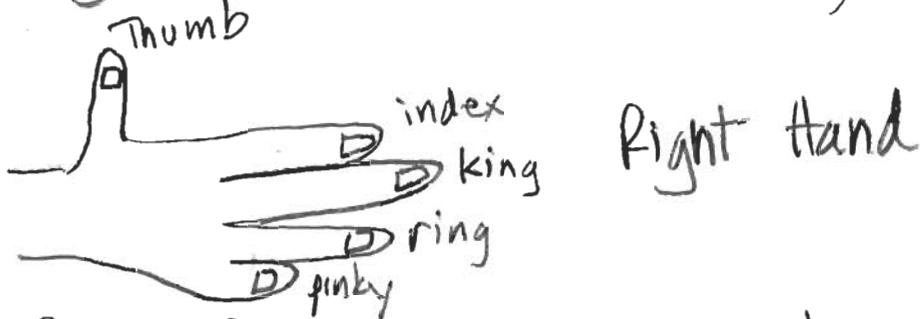
origin? For vectors, not always pertinent, because "parallel translation".

[Rotations] very important in 2-d.

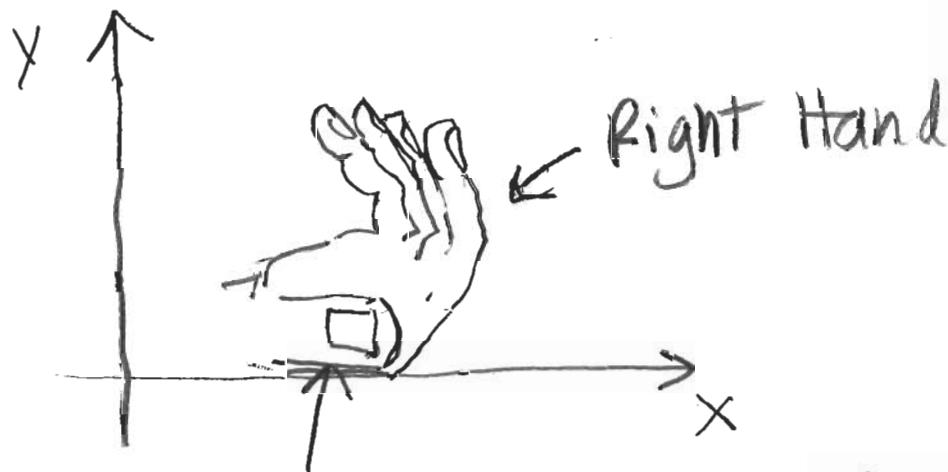


We use... "right handed" coordinate systems
(arbitrary but universal convention)

- x rotated to y goes counterclockwise
- take right hand, make it flat, thumb up:



- align four fingers in x -direction, so that when you bend them, they bend toward y -axis



Thumb sticks up, out of page... that is a right-handed coordinate system. Had you used left hand, then your thumb would have poked down into page.

(If you look at a left handed coordinate system from under the page, it looks right handed! Hmm... handedness is related to 3 dimensions!)