

"Constraint"

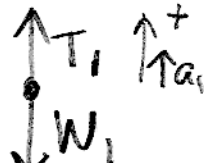
Magnitude of #1's acceleration is same as #2's

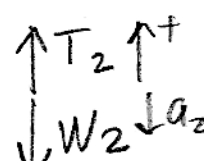
⇒ rope does not stretch


$$a_1 = a_2 \quad (1)$$

Given: m_1, m_2, g

Find: T_1, T_2, a_1, a_2 (4)

#1:  $T_1 - W_1 = m_1 a_1 \quad (2)$

#2:  $T_2 - W_2 = -m_2 a_2 \quad (3)$

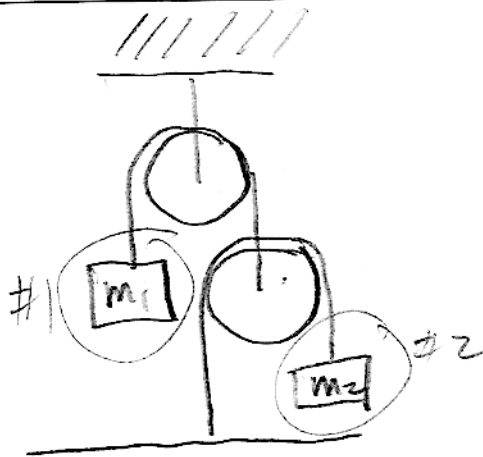
#3:  $T_1 - T_2 = 0$
 $T_1 = T_2 \quad (4)$

$$a_1 = a_2 = \frac{(m_2 - m_1)}{m_1 + m_2} g \quad \text{check sign}$$

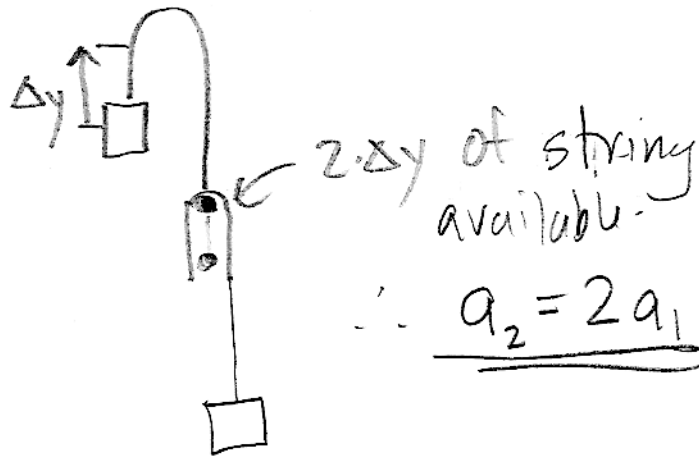
$$T_1 = T_2 = 2 \frac{m_1 m_2}{m_1 + m_2} g = 2\mu g$$

Remove ["Global *"]

Solve $\{a_2 = a_1, T_1 - m_1 g = m_1 a_1, T_2 - m_2 g = -m_2 a_2, T_1 = 2 T_2\}$
 $\{a_1, a_2, T_1, T_2\}$



$a_1 + a_2$ related



$\therefore \underline{a_2 = 2a_1}$ #1

#1: $\begin{matrix} \uparrow T_1 \\ \downarrow W_1 \end{matrix} \begin{matrix} \uparrow a_1 \\ \downarrow a_2 \end{matrix} \quad \begin{matrix} T_1 - W_1 = m_1 a_1 \\ T_1 - m_1 g = m_1 a_1 \end{matrix}$

#2: $\begin{matrix} \uparrow T_1 \\ \downarrow W_1 \end{matrix} \begin{matrix} \downarrow a_2 \end{matrix} \quad T_1 - m_2 g = m_2 a_2$

#3 massless pulley: $\begin{matrix} \uparrow T_1 \\ T_2 \downarrow \downarrow T_2 \end{matrix} \quad \begin{matrix} T_1 - 2T_2 = 0 \\ T_1 = 2T_2 \end{matrix}$

$$a_1 = - \frac{(m_1 - 2m_2)}{m_1 + 4m_2} g = \frac{2m_2 - m_1}{m_1 + 4m_2} g$$

$$a_2 = 2a_1 = -2 \frac{(2m_2 - m_1)}{m_1 + 4m_2} g$$

$$T_1 = \frac{6m_1 m_2}{m_1 + 4m_2} g$$

$$T_2 = \frac{1}{2} T_1 = \frac{3m_1 m_2}{m_1 + 4m_2} g$$