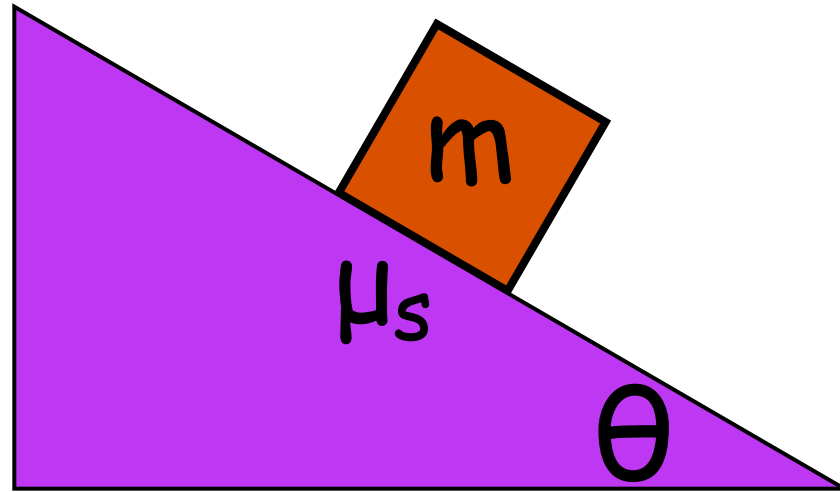


Incline of infinite mass, non-zero static friction. Call the magnitude of the frictional force f and assume the block is not moving. Newton's law in *vertical* is:

- A. $-mg \cos \theta + N = 0$
- B. $-mg + N \cos \theta = 0$
- C. $N \sin \theta - f \cos \theta = mg \sin \theta$
- D. $N \sin \theta = mg \sin \theta$
- E. $N \cos \theta + f \sin \theta - mg = 0$



Incline of infinite mass, non-zero static friction. Call the magnitude of the frictional force f and assume the block is not moving. Newton's law in *horizontal* is:

- A. $-f + mg \sin \theta = 0$
- B. $-f \sin \theta + mg = 0$
- C. $N \sin \theta - f \cos \theta = 0$
- D. $N \sin \theta - f \sin \theta = mg \cos \theta$
- E. $N \cos \theta - mg + f \sin \theta = 0$

$$f_s \leq \mu_s N$$

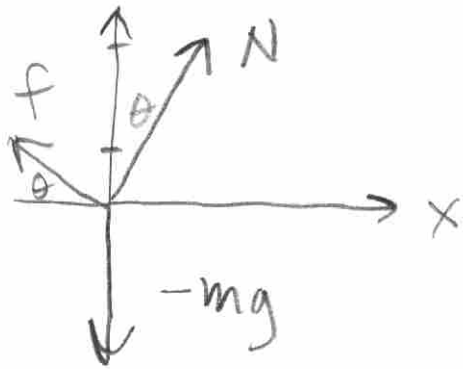
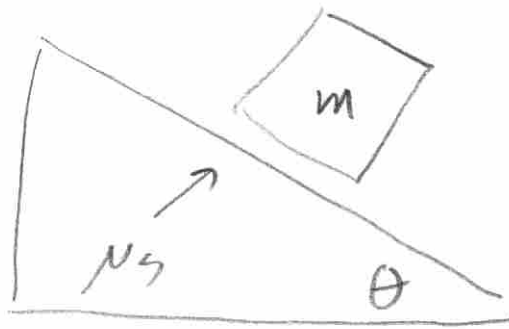
When F exceeds $\mu_s N$, sliding starts..

$$f_k = \mu_k N$$

Generally, $\mu_k < \mu_s$

Don't skid!

	μ_s	μ_k
Wood/Wood	0.25-0.5	0.2
Glass/Glass	0.9-1.0	0.4
Steel/Steel clean	0.6	0.6
" lub.	0.09	0.05
Rubber on <u>dry</u>	1.0	0.8
Ski on snow	0.04	0.04
Teflon/Teflon	0.04	0.04



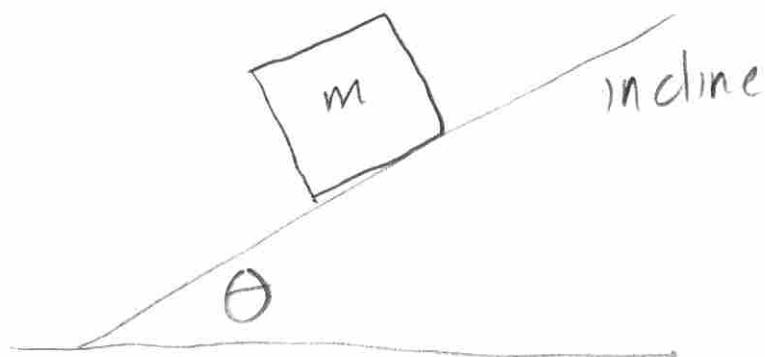
vertical :

$$N \cos \theta + f \sin \theta - mg = 0$$

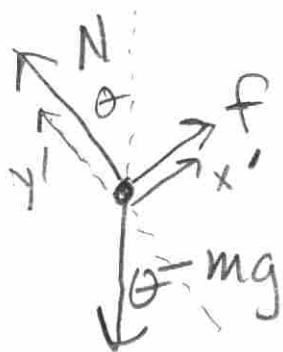
horizontal

$$N \sin \theta - f \cos \theta = 0$$

To determine μ_s



increase θ until mass slides



$$|f| \leq |\mu_s N|$$

$$N - mg \cos \theta = 0$$

$$f - mg \sin \theta = 0 \quad \text{static}$$

$$N = mg \cos \theta$$

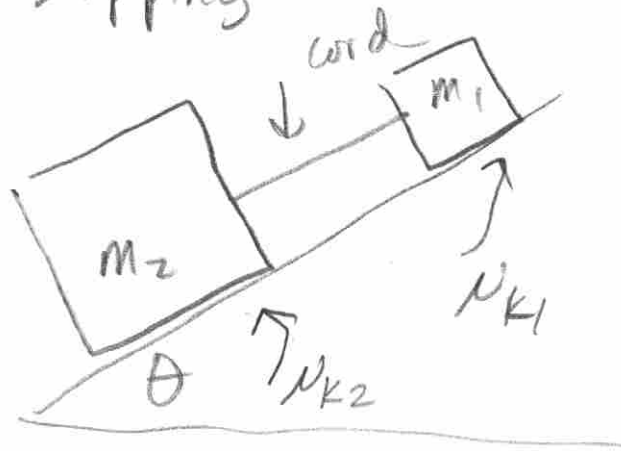
$$f = mg \sin \theta$$

$$\frac{f}{N} = \frac{mg \sin \theta}{mg \cos \theta} = \tan \theta = \mu_s \quad \text{slippage}$$

do demo!

AFTER SLIPPING STARTS ...
accelerates ...

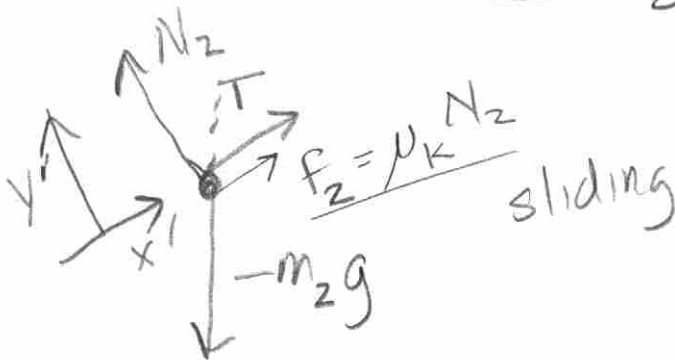
When slipping - -



Tension in cord? Acceleration?

Assume $\tan \theta > \mu_k$

$\mu_k = 0$?? $a = g \sin \theta$ BOTH!



$$N_2 - m_2 g \cos \theta = 0$$

$$N_2 = m_2 g \cos \theta$$

$$-m_2 \ddot{x}' = -m_2 g \sin \theta + \mu_{k2} m_2 g \cos \theta + T$$

↓

$$-m_1 \ddot{x}' = -m_1 g \sin \theta + \mu_{k1} m_1 g \cos \theta - T$$

$$\ddot{x}' = g \sin \theta - \mu_{k2} g \cos \theta + \frac{T}{m_2} \quad \ddot{x}' = g \sin \theta - \mu_{k1} g \cos \theta + \frac{T}{m_1}$$

$$-\mu_{k2} g \cos \theta - \frac{T}{m_2} = -\mu_{k1} g \cos \theta + \frac{T}{m_1}$$

$$T \left(\frac{1}{m_1} + \frac{1}{m_2} \right) = (\mu_{k1} - \mu_{k2}) g \cos \theta$$

reduced
mass

$$\frac{1}{\nu} \equiv \frac{1}{m_1} + \frac{1}{m_2}$$

ν ... not coefficient
of friction'

$$T = \nu (\mu_{k1} - \mu_{k2}) g \cos \theta$$

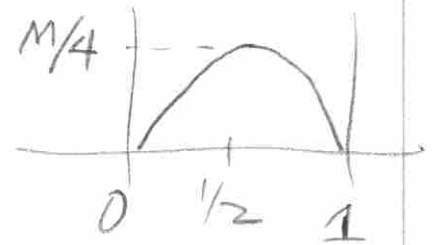
let $m_1 = FM$ $m_2 = (1-F)M$ hold M
constant

vary F

$$\frac{1}{\nu} = \frac{1}{FM} + \frac{1}{(1-F)M}$$

$$= \frac{(1-F) + F}{F(1-F)M} = \frac{1}{F(1-F)M}$$

$$\nu = F(1-F)M$$



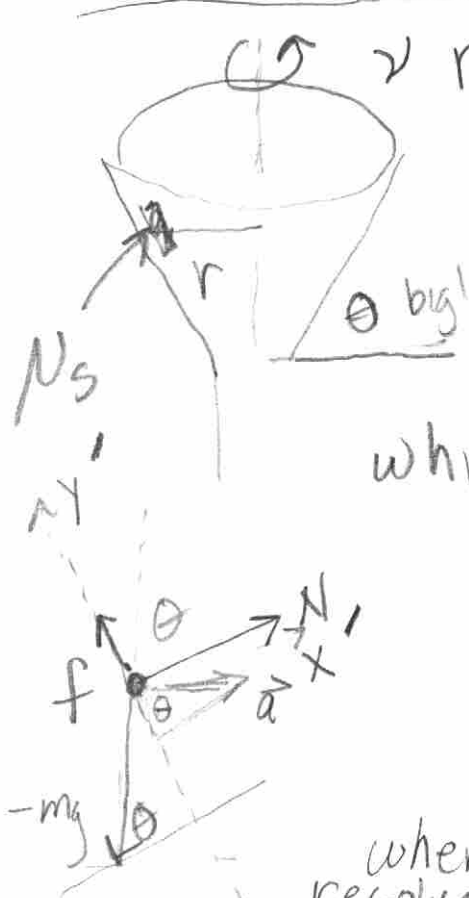
$$\ddot{x}' = g \sin \theta - \mu_{k2} g \cos \theta - \frac{m_1 m_2}{m_2 (m_1 + m_2)} (\mu_{k1} - \mu_{k2}) g \cos \theta$$

$$= g \sin \theta - \left(1 - \frac{m_1}{m_1 + m_2}\right) \mu_{k2} g \cos \theta - \frac{m_1}{m_1 + m_2} \mu_{k1} g \cos \theta$$

$$\ddot{x}' = g \sin \theta - \left(\frac{m_2}{m_1 + m_2} \mu_{k2} + \frac{m_1}{m_1 + m_2} \mu_{k1} \right) g \cos \theta$$

Tile in a funnel

PHY4 6.53


 ω revolutions per second $\Rightarrow 2\pi\omega$ $\frac{\text{radians}}{\text{s}}$

$$\omega = 2\pi\omega$$

Find largest, smallest values of ω for which the tile stays put.

$$|a| = \omega^2 r = 4\pi^2 \omega^2 r$$

a known

Tip: work in frame (axes) where unknowns need not be resolved.

$$y': f - mg \sin \theta = -ma \cos \theta$$

$$f = m(g \sin \theta - a \cos \theta)$$

$$x': N - mg \cos \theta = ma \sin \theta \quad \rightarrow \text{note meanings}$$

$$N = m(g \cos \theta + a \sin \theta)$$

$$\left| \frac{f}{N} \right| < \mu_s$$

$$-\mu_s < \frac{g \sin \theta - a \cos \theta}{g \cos \theta + a \sin \theta} < \mu_s$$

$$-\mu_s < \frac{g \tan \theta - a}{g + a \tan \theta} < \mu_s$$

$$\mu_s (g + a \tan \theta) < g \tan \theta - a < \mu_s (g + a \tan \theta)$$

$$\downarrow$$

$$\downarrow$$

$$a(\mu_s \tan \theta + 1) < g(\tan \theta + \mu_s) \quad g(\tan \theta - \mu_s) < a(1 + \mu_s \tan \theta)$$

$$a < g \frac{\mu_s + \tan \theta}{-\mu_s \tan \theta + 1}$$

$$a > g \frac{\tan \theta - \mu_s}{1 + \mu_s \tan \theta}$$

$$g \frac{\tan \theta - \mu_s}{1 + \mu_s \tan \theta} <$$

$$4\pi^2 v^2 r < g \frac{\tan \theta + \mu_s}{1 - \mu_s \tan \theta}$$

$$\frac{1}{2\pi} \left[\frac{g \tan \theta - \mu_s}{r (1 + \mu_s \tan \theta)} \right]^{1/2} <$$

$$v < \frac{1}{2\pi} \left[\frac{g \tan \theta + \mu_s}{r (1 - \mu_s \tan \theta)} \right]^{1/2}$$